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## Outline

Introduction  
Path-based distances  
Local  $B$ - and  $B^*$ -maxima  
Examples  
Conclusions

# Sparse Object Representations by Digital Distance Functions

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April 8, 2011



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UNIVERSITET

## Outline

Introduction  
Path-based distances  
Local  $B$ - and  $B^*$ -maxima  
Examples  
Conclusions

# Contents

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions



UPPSALA  
UNIVERSITET

## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Introduction

- ▶ Skeletons
  - ▶ Thin
  - ▶ Centered
  - ▶ Topology preserving
  - ▶ Reversible – anchor points
- ▶ Digital distance functions



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UNIVERSITET

## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Introduction

- ▶ **Skeletons**
  - ▶ Thin
  - ▶ Centered
  - ▶ Topology preserving
  - ▶ Reversible – anchor points
- ▶ Digital distance functions



UPPSALA  
UNIVERSITET

## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Introduction

- ▶ Skeletons
  - ▶ Thin
  - ▶ Centered
  - ▶ Topology preserving
  - ▶ Reversible – anchor points
- ▶ Digital distance functions



## Outline

Introduction

Path-based distances

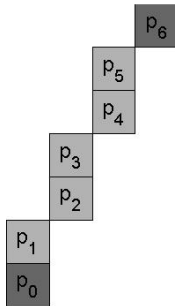
Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Weighted distances

The path below is a minimal cost path between  $\mathbf{p}_0$  and  $\mathbf{p}_6$  of cost  $3\alpha + 3\beta$ .





## Outline

Introduction

Path-based distances

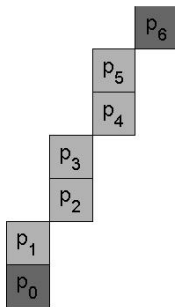
Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Distances based on neighborhood sequence

The path is a  $B$ -path for  $B = (2, 2, 2, \dots) = (2)$  and  $B = (1, 2)$ , but not for  $B = (1)$ .





## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Weighted neighborhood sequences

## Definition

Given a neighborhood sequence (ns)  $B$  and two weights  $\alpha$  and  $\beta$ , a path  $\mathcal{P}$  is a *minimal cost*  $(\alpha, \beta)$ -*weighted  $B$ -path* between two points  $\mathbf{p}$  and  $\mathbf{q}$  if

- ▶  $\mathcal{P}$  is a  $B$ -path and
- ▶ there is no other  $B$ -path between  $\mathbf{p}$  and  $\mathbf{q}$  with lower cost.





## Outline

Introduction

Path-based distances

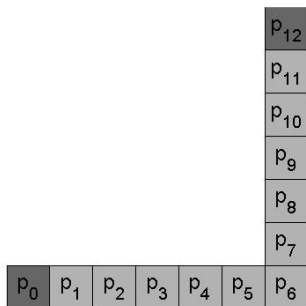
Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Weighted neighborhood sequences

Let  $B = (1, 2)$  and  $\alpha = 2, \beta = 3$ .



This path is a  $B$ -path of cost  $12\alpha = 24$ .

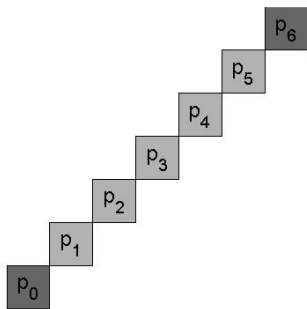


## Outline

- Introduction
- Path-based distances
- Local  $B$ - and  $B^*$ -maxima
- Examples
- Conclusions

# Weighted neighborhood sequences

Let  $B = (1, 2)$  and  $\alpha = 2, \beta = 3$ .



This path is of cost  $6\beta = 18$ . It is *not* a  $B$ -path.

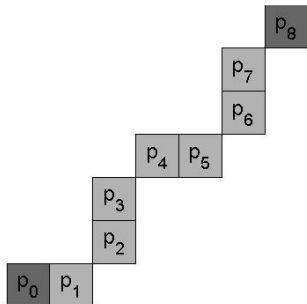


## Outline

- Introduction
- Path-based distances
- Local  $B$ - and  $B^*$ -maxima
- Examples
- Conclusions

# Weighted neighborhood sequences

Let  $B = (1, 2)$  and  $\alpha = 2, \beta = 3$ .



This path is a *minimal cost B*-path. Its cost is  $4\alpha + 4\beta = 20$ .



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## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Path-based distances



city-block



chessboard



weighted



ns



weighted ns



## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Maximal balls

- ▶ A ball in an object  $X$  is a *maximal ball* if there is no other ball in  $X$  containing.
- ▶ An object  $X$  is equal to the union of its set of *maximal balls*.
- ▶ For the weighted distance with  $\alpha = 3$  and  $\beta = 4$ , the set of centers of maximal balls can be obtained by a local check (finding the local maxima) in the distance transform. Relabeling of distance values that can not be attained is needed.
- ▶ Is this true also for (weighted) distances based on neighborhood sequences? To answer this question, we introduce the notion of maximal path-points, local  $B$ -maxima and local  $B^*$ -maxima.



## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

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## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

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## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

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## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Distance transform

$X$  is the object,  $\bar{X}$  is the background.

Given  $B$  and weights  $\alpha, \beta$ , the value of  $DT_C(\mathbf{p})$  for any point  $\mathbf{p} \in X$  is

$$\min_{\mathbf{q} \in \bar{X}} \{ \text{cost of the minimal cost } B\text{-path between } \mathbf{p} \text{ and } \mathbf{q} \} .$$



## Outline

- Introduction
- Path-based distances
- Local  $B$ - and  $B^*$ -maxima
- Examples
- Conclusions

# Local maxima

## Definition

A point  $\mathbf{p} \in X$  is a local maximum if  $DT_C(\mathbf{p}) > DT_C(\mathbf{p} + \mathbf{n}_i) - w_i$ , where the set  $\{\mathbf{n}_i\}$  defines the neighborhood at  $\mathbf{p}$  and  $w_i$  are the corresponding weights.

3	3	3	3
3	6	4	3
3	3	3	



## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

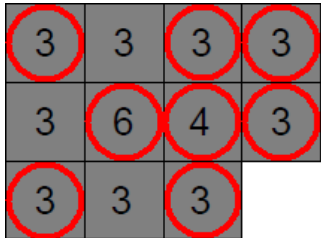
Examples

Conclusions

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## Outline

- Introduction
- Path-based distances
- Local  $B$ - and  $B^*$ -maxima
- Examples
- Conclusions

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## Relabeled distance values

1	1	1	1
1	5	4	1
1	1	1	



## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

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## Outline

- Introduction
- Path-based distances
- Local  $B$ - and  $B^*$ -maxima
- Examples
- Conclusions

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## Which neighborhood should be used?

- ▶ weighted distances – fixed neighborhood.
- ▶ ns-distances – the size of the neighborhood is determined by the length of the path = the distance value.
- ▶ weighted ns-distances – the size of the neighborhood can *not* be determined by  $DT_C$ .



## Outline

- Introduction
- Path-based distances
- Local  $B$ - and  $B^*$ -maxima
- Examples
- Conclusions

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## Outline

- Introduction
- Path-based distances
- Local  $B$ - and  $B^*$ -maxima
- Examples
- Conclusions

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## Outline

- Introduction
- Path-based distances
- Local  $B$ - and  $B^*$ -maxima
- Examples
- Conclusions

# Local maxima

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## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Maximal path-points

## Definition

A point  $\mathbf{p} \in X$  is a *maximal path-point* if there is a point  $\mathbf{q} \in \bar{X}$  such that

- ▶  $\langle \mathbf{q} = \mathbf{p}_0, \mathbf{p}_1, \dots, \mathbf{p}_n = \mathbf{p} \rangle$  is a minimal cost  $(\alpha, \beta)$ -weighted  $B$ -path of length  $n$  that defines  $DT_C(\mathbf{p})$  and
- ▶ there is no  $\mathbf{p}'$  such that  $\langle \mathbf{q} = \mathbf{p}_0, \mathbf{p}_1, \dots, \mathbf{p}_n, \mathbf{p}_{n+1} = \mathbf{p}' \rangle$  is a minimal cost  $(\alpha, \beta)$ -weighted  $B$ -path of length  $n + 1$  that defines  $DT_C(\mathbf{p}')$ .

We denote the set of maximal points by  $MP$ .



## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Maximal path-points

							2
					2	2	4
				2	4	4	5
			2	4	5	6	7
		2	4	5	7	8	9
	2	4	6	8	10	11	
2	4	5	7	9	11	13	

Figure:  $DT_C$ ,  $B = (1, 2)$  and  $(\alpha, \beta) = (2, 3)$

Path of length five.



## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Maximal path-points

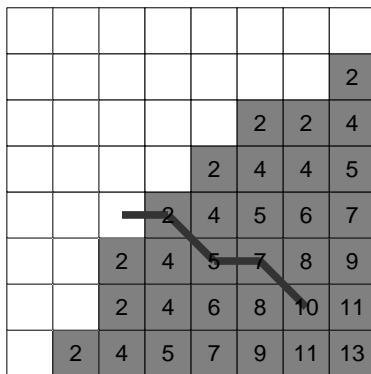


Figure:  $DT_c$ ,  $B = (1, 2)$  and  $(\alpha, \beta) = (2, 3)$

Path of length four. This path defines a maximal path point.



## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Maximal path-points

							1
					1	1	2
				1	2	2	2
			1	2	2	3	3
		1	2	2	3	4	4
		1	2	3	4	4	5
	1	2	2	3	4	5	6

Figure:  $DT_{\mathcal{L}}$ ,  $B = (1, 2)$  and  $(\alpha, \beta) = (2, 3)$



## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Representability, maximal path-points

## Theorem

*If either*

$$\alpha < \beta \leq 2\alpha \text{ or} \quad (1)$$

$$\alpha = \beta \text{ and } (B = (1) \text{ or } B = (2)), \quad (2)$$

*then  $X$  can be recovered from the set of maximal path-points.*

Note: not ns-distances in general!



## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Smallest neighborhood

## Definition

Given an object  $X$ , a ns  $B$  and weights  $\alpha, \beta$ , we say that  $DT_{\mathcal{L}}$  associated with  $DT_C$  holds information about the smallest neighborhoods if it holds information about the minimal cost-path with smallest size of the neighborhood at each point of  $X$ .



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## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Local $B$ -maxima

A local  $B$ -maximum is a local maximum obtained by using the neighborhood defined by  $b(DT_{\mathcal{L}}(\mathbf{p}) + 1)$  at the point  $\mathbf{p}$ .





## Outline

- Introduction
- Path-based distances
- Local  $B$ - and  $B^*$ -maxima
- Examples
- Conclusions

# Local $B$ -maxima

## Theorem

*If  $DT_{\mathcal{L}}$  holds information about the smallest neighborhoods, then the set of maximal path points equals the set of local  $B$ -maxima.*

This theorem gives an efficient way to compute this set of points.



## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Local $B$ -maxima

## Theorem

*If  $DT_{\mathcal{L}}$  holds information about the smallest neighborhoods, then the set of maximal path points equals the set of local  $B$ -maxima.*

This theorem gives an efficient way to compute this set of points.



## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Local $B^*$ -maxima

A local  $B^*$ -maximum is a local maximum obtained by using the neighborhood defined by  $b(DT_{\mathcal{L}}(\mathbf{p}))$  at the point  $\mathbf{p}$ .



## Outline

- Introduction
- Path-based distances
- Local  $B$ - and  $B^*$ -maxima
- Examples
- Conclusions

# Representability, local $B^*$ -maxima

## Theorem




*If  $DT_{\mathcal{L}}$  holds information about the smallest neighborhoods, then the original object can be recovered from the set of local  $B^*$ -maxima.*



## Outline

- Introduction
- Path-based distances
- Local  $B$ - and  $B^*$ -maxima
- Examples
- Conclusions

# Examples




local $B$ -maxima (the set $MP$ )	local $B^*$ -maxima	CMBs
$B = (1), (\alpha, \beta) = (1, 1)$		
 222 elements	 222 elements	 222 elements



## Outline

- Introduction
- Path-based distances
- Local  $B$ - and  $B^*$ -maxima
- Examples
- Conclusions

# Examples




local $B$ -maxima (the set $MP$ )	local $B^*$ -maxima	CMBs
$B = (2), (\alpha, \beta) = (1, 1)$		
 250 elements	 250 elements	 250 elements



## Outline

- Introduction
- Path-based distances
- Local  $B$ - and  $B^*$ -maxima
- Examples
- Conclusions

# Examples

local $B$ -maxima (the set $MP$ )	local $B^*$ -maxima	CMBs
$B = (1, 2), (\alpha, \beta) = (1, 1)$		
 418 elements	 295 elements	 295 elements



## Outline

Introduction




Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Examples

local $B$ -maxima (the set $MP$ )	local $B^*$ -maxima	CMBs
$B = (2), (\alpha, \beta) = (3, 4)$		
 453 elements	 453 elements	 317 elements








## Outline

- Introduction
- Path-based distances
- Local  $B$ - and  $B^*$ -maxima
- Examples
- Conclusions

# Examples

local $B$ -maxima (the set $MP$ )	local $B^*$ -maxima	CMBs
$B = (1, 2), (\alpha, \beta) = (2, 3)$		
 451 elements	 406 elements	 278 elements



## Outline

Introduction




Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Examples

local $B$ -maxima (the set $MP$ )	local $B^*$ -maxima	CMBs
$B = (1, 2, 1, 2, 2), (\alpha, \beta) = (4, 5)$		
 471 elements	 435 elements	 289 elements



## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Conclusions, Summary

- ▶ The maximal path-points are the points that do not propagate distance information when computing the DT.
- ▶ The set of maximal path-points  $MP$  can be computed efficiently by finding local  $B$ -maxima.
- ▶ Local  $B^*$ -maxima.
- ▶ If the weights  $\alpha$  and  $\beta$  are equal, then the set of  $B$ -maxima is not reversible.
- ▶ When a constant neighborhood sequence is used, the two approaches are equal

Future work:

- ▶ Relabeling



## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Conclusions, Summary

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## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Conclusions, Summary

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## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

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## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

# Conclusions, Summary

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## Outline

Introduction

Path-based distances

Local  $B$ - and  $B^*$ -maxima

Examples

Conclusions

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